# Reconstruction in MicroBooNE using OpenCV Image Processing







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New Perspectives 2016





#### Motivation

#### Why $\pi$ 0?

 Important background to understand for low energy excess search

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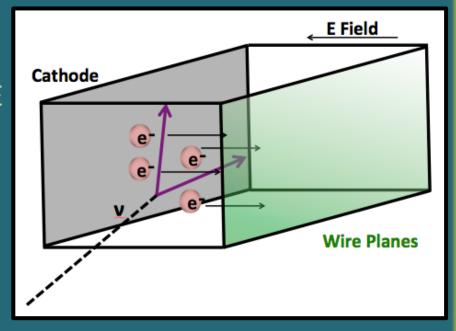
 Can learn about particle that produced electromagnetic showers by looking at shower energies (E1, E2) and 3D opening angle (Θ<sub>Υγ</sub>)

$$m_{\pi^0} = \sqrt{2E_1E_2\left(1-\cos heta_{\gamma\gamma}
ight)}$$

#### Motivation

MicroBooNE is a Liquid Argon Time Projection Chamber (see D. Caratelli's talk "MicroBooNE in 10 Minutes")

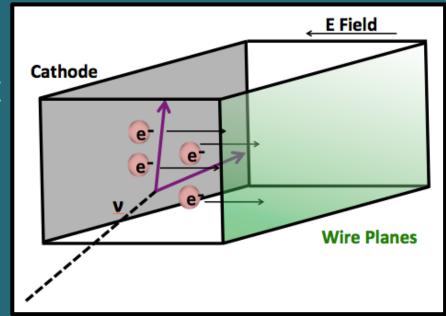
Ionization charge drifted to wire planes contains interaction information

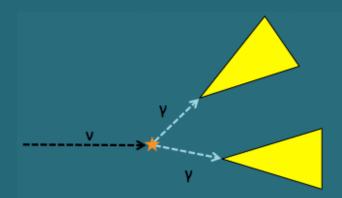


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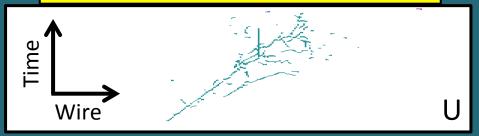


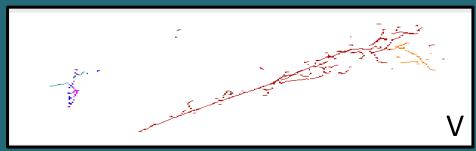


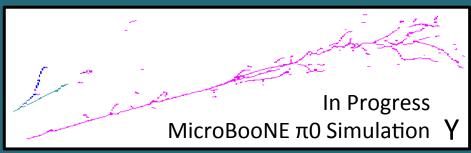
How can we group charge depositions meaningfully?

# Motivation – Clustering Example

#### Traditional (Fuzzy) Clustering







Traditional clustering output suggests many cluster topologies to account for in downstream algorithms

Can we do better?

Note : Colors represent individual clusters and are uncorrelated across planes

#### Outline

- 0) Motivation
- 1) What is OpenCV?
- Clustering hits with image processing
- 3) Parameter Finding
- 4) Reconstruction



# What is OpenCV?



- Open source computer vision library
- Functions and classes to aid in pattern recognition and image processing
- World wide community contributing to algorithm development
- Efficient, fast and easy to use

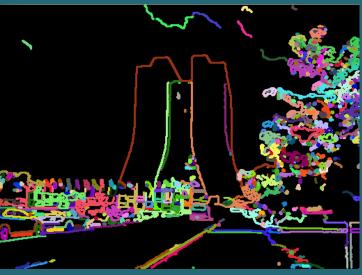
# Examples of OpenCV in Action





Example of Canny edge detection

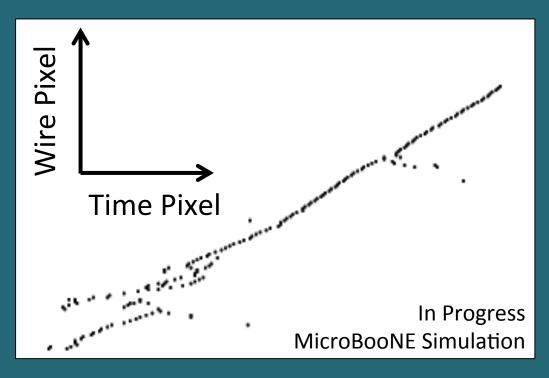




Example of contour finding; each color represents contour

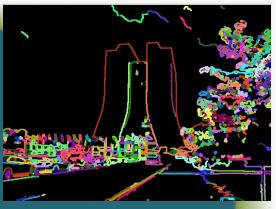
#### Outline

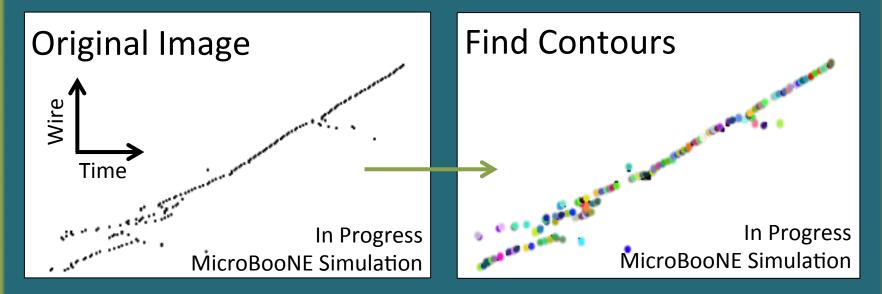
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- Size of image determined by wire and time tick ranges
- Scale charge to 8
   bits; this results in
   single channel
   gray scale image

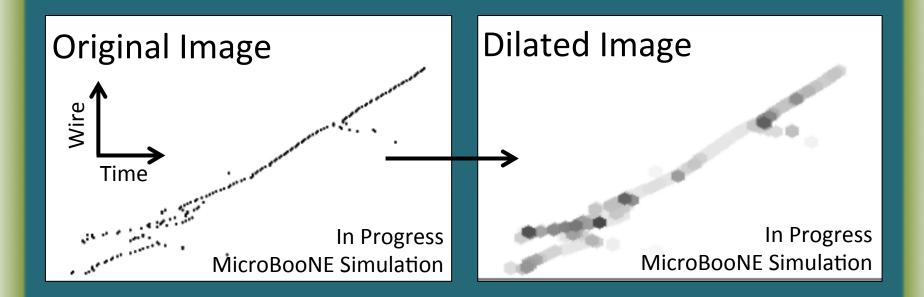
OpenCV Function: "findContours"





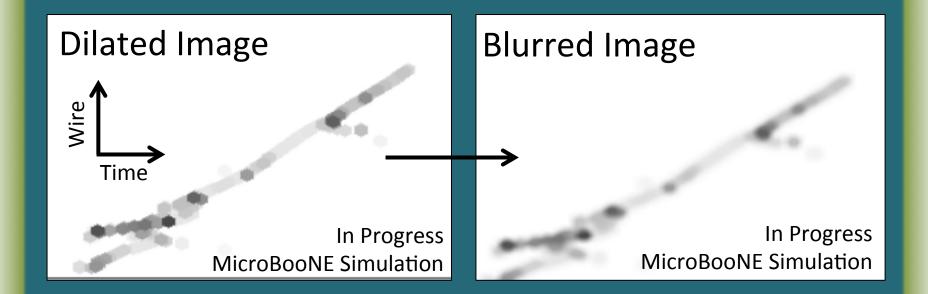
**Conclusion**: Initial image is too granular; need to manipulate image prior to contour finding

OpenCV Function: "dilate"



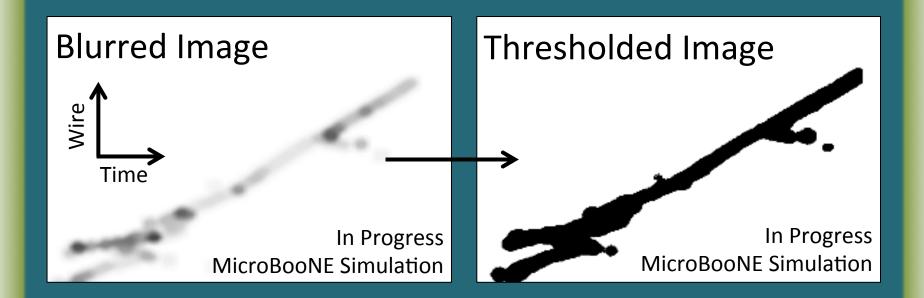
<u>Dilation</u>: Set pixels within dilation radius around hit to grayscale value of that hit to connect hits

OpenCV Function: "blur"



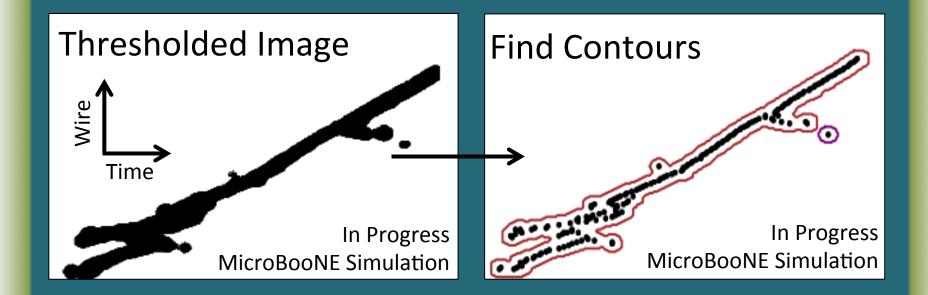
Blur: Gaussian filter smoothes edges of dilated image

OpenCV Function: "threshold"



Threshold: Convert pixels above some grayscale threshold value to 1's, those below to 0's.

OpenCV Function: "findContours"

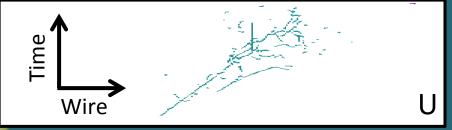


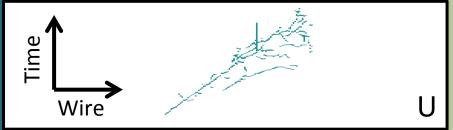
**Contours:** Lastly, we apply contour finding on the thresholded image and associate pixels to each contour

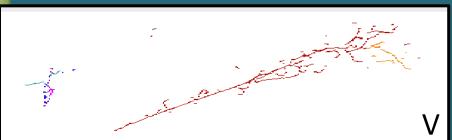
# Clustering Comparison

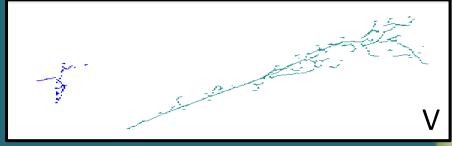


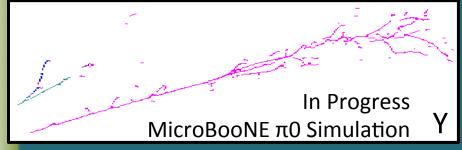
**OpenCV Clustering** 











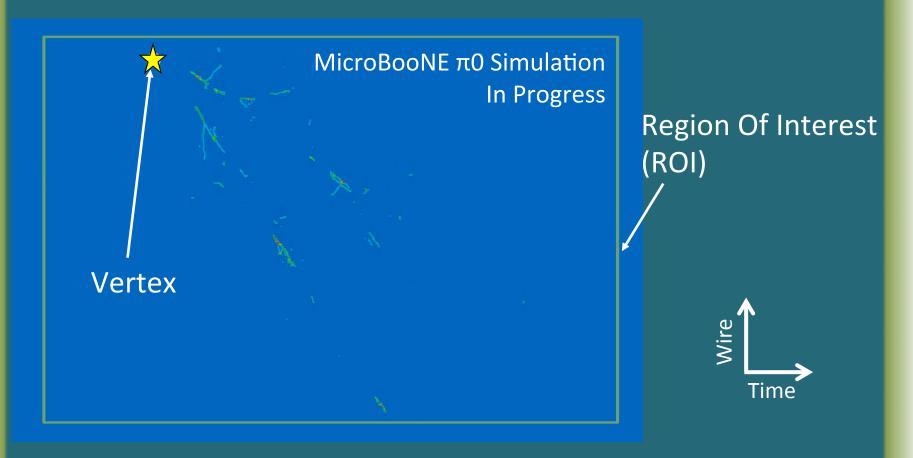


OpenCV does better job in the first pass of clustering!

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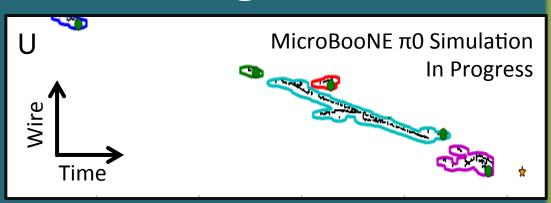
#### Parameter Finding – Region Of Interest



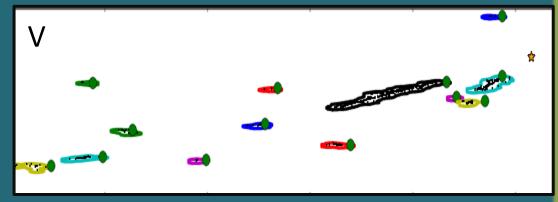
Can deterministically cluster if passed an ROI by selection algorithms, Deep Learning, etc

# Parameter Finding – ROI

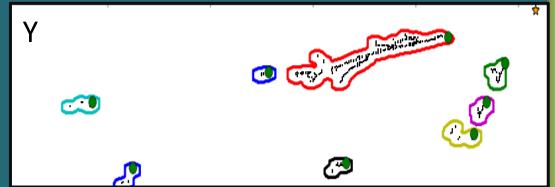
Can use interaction vertex from ROI to assign cluster start point, direction



Colors uncorrelated

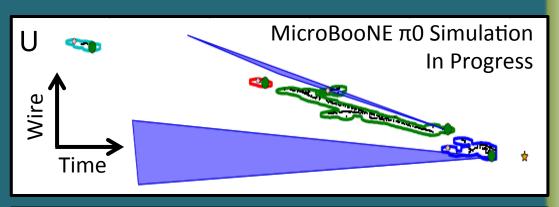


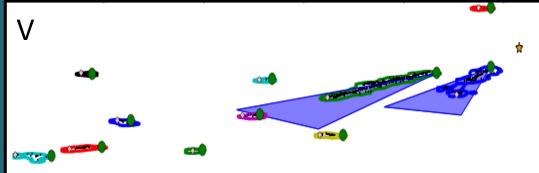




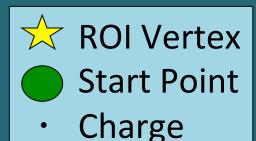
# Merge Missing Charge

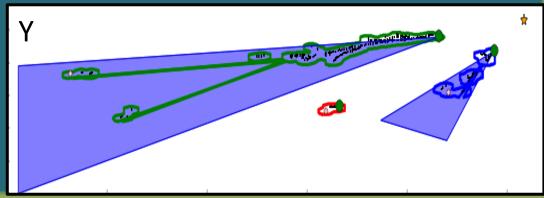
Expand triangle from start point along direction to merge excess charge





#### Colors uncorrelated

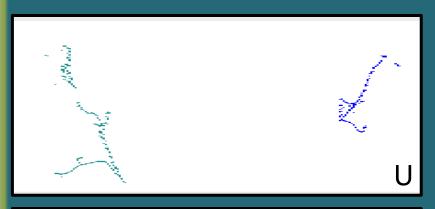


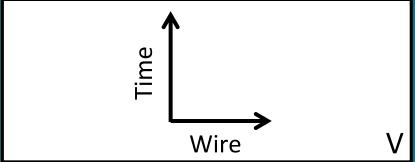


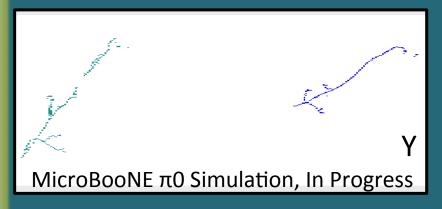
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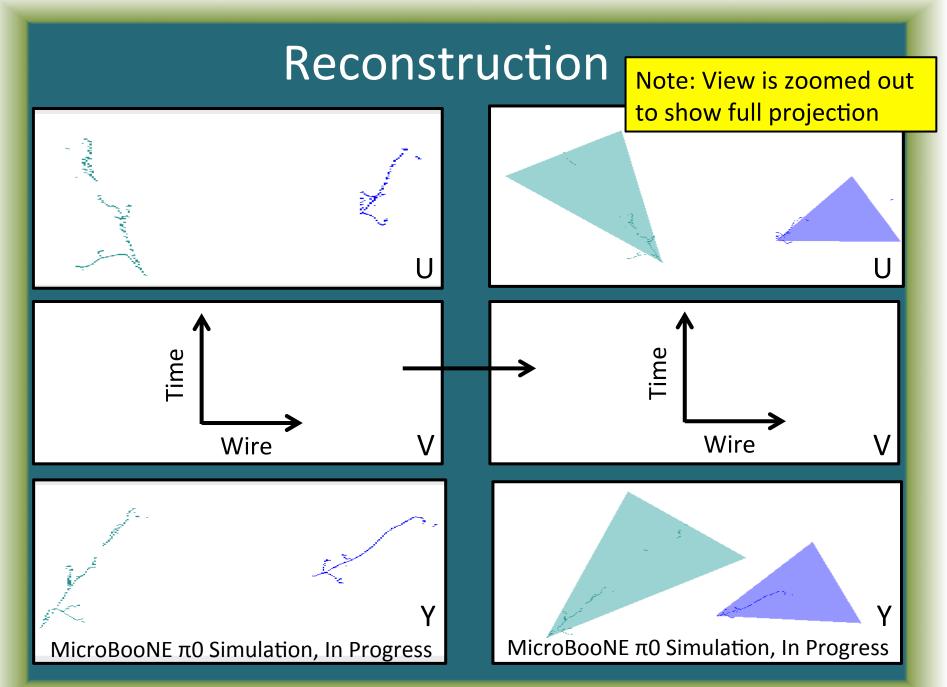
#### Cluster Matching







- Only need two planes to do reconstruction; in this case, matches are found between planes U and Y
- Clusters matched according to similarity in shared coordinate, time



#### Conclusion

- OpenCV is pattern recognition software with easy to use algorithms and classes.
- We can use OpenCV to manipulate our event images, contour find, and form clusters.
- OpenCV identified clusters can be assigned parameters and successfully reconstructed for use in physics analysis

